



eXtended eXternal Benchmarking eXtension (XXBX)

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DIAC 2015





Outline

Introduction & Motivation

- Introduction
- Motivation
- 2 Previous Work
 - SUPERCOP
 - XBX
 - FELICS
- 3 XXBX
 - Design Goals
 - Hardware
 - Software
 - Power Measurement
- 4 Conclusions and Future Work
 - Conclusions
 - Future Work



Introduction Motivation



Introduction & Motivation



Introduction Motivation



Introduction

- XXBX is a tool for benchmarking algorithms on microcontrollers that cannot efficiently run their own operating system and compilers.
- It uses the following Metrics:
 - Throughput cycles per byte
 - ROM usage bytes
 - RAM usage bytes
 - Power milliwatts



ххвх



Introduction Motivation



Motivation

- IoT promises a dramatic increase in devices, many will be microcontrollers or SOCs.
- 32-bit microcontrollers are projected to take lead over 8/16-bit by 2018.
- 51% of all 32-bit microcontrollers were ARM based in 2012.



Global internet device installed base forecast

Sep 29th,2015

XXBX



SUPERCOP XBX FELICS



Previous Work

Sep 29th,2015



SUPERCOP

SUPERCOP XBX FELICS



- System for Unified Performance Evaluation Related to Cryptographic Operations and Primitives.
- Benchmarks many implementations of many primitives across multiple operations on multiple hardware platforms.
- Supports environments capable of running Linux and hosting a compiler.
- Series of shell scripts and C test harnesses, and comprehensive collection of algorithm primitive implementations.
- Verifies correct execution of implementations and times cycles required per byte processed.
- Does not measure ROM and RAM usage or power consumption.

http://bench.cr.yp.to/supercop.html



XBX

SUPERCOP XBX FELICS



- eXternal Benchmarking eXtension -extends SUPERCOP
- Automated testing on real microcontrollers
- Compatibility with SUPERCOP algorithm collection ("algopacks") and output format
- Low cost hardware and software
- Our contribution to original XBX was to port it to the MSP430 platform and provide results for SHA-3 finalists.
- Measures ROM and RAM usage. Does not measure power consumption.



SUPERCOP XBX FELICS



XBX Components



Figure : Block Diagram of XBX components



SUPERCOP XBX FELICS



XBX Limitations

- Only supports hash functions
- No power measurements
- Does not use cycle counters
- Benchmarking takes a long time because embedded platforms are slow.
 - Simulation can run faster



Figure : AVR-NET-IO ATmega32 board with MSP430





SUPERCOP XBX FELICS



- Fair Evaluation of Lightweight Cryptographic System
- Targeted for lightweight block ciphers
- Uses simulation when available else real hardware
- Supports Atmel AVR, MSP 430, ARM Cortex-M3
- Measures RAM, ROM, execution time.

https://www.cryptolux.org/index.php/FELICS



Design Goals Hardware Software Power Measurement







Design Goals Hardware Software Power Measurement



Design Goals

- Add AEAD support
- Add power measurement
- Replace XBH in order to facilitate power measurement
- Add resuming partial runs
- Avoid breaking when Link-Time Optimization is enabled
- XBXX? :)



Design Goals Hardware Software Power Measurement



XBH Replacements

- \bullet Requires ethernet and I/O to XBD
- Hardware under initial consideration
 - Raspberry Pi
 - Beaglebone
- Linux-based boards very fast, but do not easily meet real-time requirements
- Tiva Connected Launchpad chosen when it became available
 - ARM Cortex-M4F with ethernet connectivity.
 - 256kiB of SRAM and 1MiB of ROM
 - Dual 12-bit ADCs capable of 2 MSPS
 - Easily worked on bare metal without an OS



Design Goals Hardware Software Power Measurement





Figure : Tiva C Connected Launchpad



Design Goals Hardware Software Power Measurement



XBD Hardware

- MSP-EXP430F5529LP
 - 16-bit MSP430 clockable to 25MHz, 10kiB SRAM and 128kiB flash
- EK-TM4C123GXL
 - 32-bit ARM Cortex M4F clockable to 80MHz, 32kiB SRAM and 128kiB flash
- Both of these newer versions of what is currently supported by XBX
- TODO: Support AVR, MIPS
- XBX also supports ARM Cortex-A which we don't intend to support yet. Regular SUPERCOP may run on some of these.



XBH Software

Design Goals Hardware Software Power Measurement



- Use FreeRTOS with LwIP instead of bare-metal
 - Easier multitasking- OS handles task switching instead of doing it explicitly
 - Easier to write network code LwIP socket API can be used
 - LwIP and FreeRTOS port included in examples provided by Texas Instruments
- Original XBX used webserver-uvm from Ulrich Radig
- Hardware abstracted away



Design Goals Hardware Software Power Measurement



XBH code differences

- \bullet Only support TCP/IP for XBS \leftrightarrow XBH comms
- Only support I²C for XBH \leftrightarrow XBD
- Add length prefix to delimit messages
- Power measurements streamed to XBS



Design Goals Hardware Software Power Measurement



XBH code tasks

- IwIP TCP/IP
- XBH Server
- XBH command execution and XBD communication (same priority as XBH server)
- Ethernet Receive/Transmit sends transmit and receive descriptors to lwIP
- Power Measurement woken up periodically by timer interrupt to perform measurements and enqueuing them to the XBH server task.



Design Goals Hardware Software Power Measurement



XBH Interrupts

- Unused
- Timer Wraparound
- O Timer Capture
- Max FreeRTOS SysCall Priority
- Over Sample Timer
- Watchdog
- Onused
- Onused
- FreeRTOS kernel



Design Goals Hardware Software Power Measurement



XBD Software

- Largely the same as original XBX
- Replaced self-test implementation with SUPERCOP's
- Refactor out hash-specific code to make it easier to add other operations
- Add AEAD payload processing
 - XBH doesn't know anything about the operation under test, just routes it blindly to XBD from XBS.
 - XBD must know what is being in run order to unpack parameters and messages



XBH Software

Design Goals Hardware Software Power Measurement



- Completely rewritten in Python 3
- Now supports resuming runs if run fails and XBS crashes due to hung hardware
- Results now stored in a SQLite database
- Dropped unused features such as KAT-file verification and loading XBD in formats other than IHEX
- Builds performed in parallel



Design Goals Hardware Software Power Measurement



Current Sensing

- Measured by sensing voltage drop across a small shunt resistor
- High side
 - Directly measures current delivered by voltages source
 - Multiple ground paths do not need to be accounted for
 - $\bullet~$ No issues w/ ground loops
 - Must handle common-mode voltage
- Low side
 - Can be single-ended
 - Does not have to deal with common mode voltage
- We chose the high side configuration, as I/O pins could provide alternate ground paths causing measurement errors.



Design Goals Hardware Software Power Measurement



High side vs Low side





Design Goals Hardware Software Power Measurement



Current Sensor

- Utilize ADCs on Launchpad
 - These ADCs have input low-impedance, must be buffered
 - Need amplification, as shunt drop is low
- Considered putting op-amp in front of ADCs
 - Requires precision resistor network
 - More parts to deal with
- Use current sense amplifier in front of ADC specifically INA225
 - Selectable gain to adjust for different target devices in different ranges (25-200), buffered output to deal with low ADC input impedance



INA225

Introduction & Motivation Previous Work XXBX Conclusions and Future Work Design Goals Hardware Software Power Measurement





Figure : Power measurement circuit using INA225



Conclusions Future Work



Conclusions and Future Work



Conclusions Future Work



Conclusions

- XBX extended to include support for AEAD
- Enables benchmarking of power
- Allows resuming partial runs



Conclusions Future Work



SUPERCOP, XBX, XXBX Feature Comparison

| | SUPERCOP | XBX | XXBX | | |
|-----------------------|----------------|--------------|--------------|--|--|
| Target Platform | Desktop/Server | Embedded | Embedded | | |
| Speed Benchmarks | \checkmark | \checkmark | \checkmark | | |
| Memory Benchmarks | | \checkmark | \checkmark | | |
| ROM Benchmarks | N/A | \checkmark | \checkmark | | |
| Supports AEAD | \checkmark | | \checkmark | | |
| Power Benchmarks | | | \checkmark | | |



Conclusions Future Work



XBX-XBD and XXBX-XBD Comparison

| XBX Supports | | | | | | | | | |
|--------------|-------|--------------|---------------|---------|--------|---------|-------|-------|--|
| Device | | Chip | ISA | | Bus | f | OS | Price | |
| | Atmel | ATmega1284P | AVR | | 8-bit | 20 MHz | bare | | |
| Exp.Board | ті | MSP430FG4618 | MSP430 | | 16-bit | 8 MHz | bare | \$117 | |
| FritzBox | ТІ | AR7 | MIPS32 | 4KEc | 32-bit | | Linux | \$300 | |
| Artila M501 | Atmel | AT91RM9200 | ARM920T | ARMv4T | 32-bit | 180 MHz | Linux | \$116 | |
| NSLU2 | Intel | IXP420 | XScale | ARMv5TE | 32-bit | 266 MHz | Linux | \$90 | |
| | IXP | LPC1114 | ARM Cortex-M0 | ARMv6-M | 32-bit | 50 MHz | bare | | |
| | ті | LM3S811 | ARM Cortex-M3 | ARMv7-M | 32-bit | 120 MHz | bare | | |
| BeagleBoard | ті | DM3730 | ARM Cortex-A8 | ARMv7-A | 32-bit | 1 GHz | Linux | \$89 | |

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XXBX Supports

| Device | Chip | | ISA | Bus | f | OS | Price | | |
|-----------|-----------|-----------------|---------------|----------|--------|--------|-------|------|--|
| Launchpad | TI | MSP430FR6989 | MSP430 | | 16-bit | 16 MHz | bare | \$18 | |
| Launchpad | ТΙ | TM4C123GXL | ARM Cortex-M4 | ARMv7E-M | 32-bit | 80 MHz | bare | \$13 | |
| Future | Atmel | ATmega1284P | AVR | | 8-bit | 20 MHz | bare | | |
| MikroE | Microchip | PIC32MX360F064H | MIPS32 | M4K | 32-bit | 80 MHz | bare | \$25 | |
| | | | | | | | | | |



Conclusions Future Work



Remaining work

- Integrate the power measurement hardware
- Perform a full benchmarking run on all AEAD and hash algorithms that have implementations that can run
- Extend platform support to AVR
- Documentation.



Conclusions Future Work



Thanks for your attention.